Asymptotic behavior of the solution of quasilinear parametric variational inequalities in a beam with a thin neck

Iuliana Marchis

Babeş-Bolyai University
Faculty of Psychology and Educational Sciences
Str. Kogalniceanu, Nr. 4
400084 Cluj-Napoca, Romania
email: krokusz@gmail.com

Abstract. In this paper we study the asymptotic behavior of the solution of quasilinear parametric variational inequalities posed in a cylinder with a thin neck, and we obtain the limit problem.

1 Introduction

The aim of the paper is to study the asymptotic behavior of the solution of quasilinear variational inequalities in a beam with a thin neck. Mathematically, this notched beam is given by

$$\Omega_\epsilon = \{(x_1, x') \in \mathbb{R}^3 : -1 < x_1 < 1, |x'| < \epsilon \text{ if } |x_1| > t_\epsilon, |x'| < \epsilon r_\epsilon \text{ if } |x_1| \le t_\epsilon\},$$

where ϵ, r_ϵ, and t_ϵ are positive parameters such that $\frac{\epsilon r_\epsilon}{t_\epsilon} \to 0$.

Previous work on domains of this type was done by Hale & Vegas [7], Jimbo [8, 9], Cabib, Freddi, Morassi, & Percivale [2], Rubinstein, Schatzman & Sternberg [13], Casado-Díaz, Luna-Laynez & Murat [3, 4] and Kohn & Slastikov [10].

The most recent results are of Casado-Díaz, Luna-Laynez & Murat [4]. They studied the asymptotic behavior of the solution of a diffusion equation in the notched beam Ω_ϵ and obtained at the limit a one-dimensional model.

In the present article the geometrical setting is the same as in [4], but we consider quasilinear variational inequalities instead of linear variational equalities.

The paper is organized as follows. In Section 2 the geometrical setting is described, the studied problem is given, and the assumptions for our results are formulated. In Section 3 the asymptotic behavior of the solution is studied. Some results from [11] are recalled which, unfortunately, don't provide information about what happening near to the notch. Thus we need to prove some auxiliary results. In Section 4 the limit problem is obtained. To prove the results in this section, we combine the ideas from [5] with the adaptation to variational inequalities of the method used in [4].

2   Setting the problem

Let $\epsilon > 0$ be a parameter, r_ϵ ($r_\epsilon > 0$) and t_ϵ ($t_\epsilon > 0$) be two sequences of real numbers, with

$$r_\epsilon \to 0, \qquad t_\epsilon \to 0, \quad \text{when } \epsilon \to 0.$$

We assume that

$$\frac{t_\epsilon}{r_\epsilon^2} \to \mu, \quad \frac{\epsilon}{r_\epsilon} \to \nu, \quad \text{with } 0 \leq \mu < +\infty,\ 0 \leq \nu < +\infty, \quad \text{when } \epsilon \to 0.$$

Let $S \subset \mathbb{R}^2$ be a bounded domain such that $0 \in S$, which is sufficiently smooth to apply the Poincaré-Wirtinger inequality.

Define the following subsets of $\mathbb{R}^3$:

$$\Omega_\epsilon^- = (-1, -t_\epsilon) \times (\epsilon S), \quad \Omega_\epsilon^0 = [-t_\epsilon, t_\epsilon] \times (\epsilon r_\epsilon S), \quad \Omega_\epsilon^+ = (t_\epsilon, 1) \times (\epsilon S),$$

$$\Omega_\epsilon = \Omega_\epsilon^- \cup \Omega_\epsilon^0 \cup \Omega_\epsilon^+, \quad \text{and} \quad \Omega_\epsilon = \Omega_\epsilon^- \cup \Omega_\epsilon^+.$$

Ω_ϵ is a notched beam, the main part of the beam is Ω_ϵ^1 and the notched part Ω_ϵ^0. A point of Ω^ϵ is denoted by $x = (x_1, x') = (x_1, x_2, x_3)$.

Denote by
$$\Gamma_\epsilon^- = \{-1\} \times (\epsilon S) \quad \text{and} \quad \Gamma_\epsilon^+ = \{1\} \times (\epsilon S)$$

the two bases of the beam, and let

$$\Gamma_\epsilon = \Gamma_\epsilon^- \cup \Gamma_\epsilon^+$$

be the union of the two bases.

Denote

$$\mathcal{V}_\epsilon = \{V \in H^1(\Omega_\epsilon), \quad V = 0 \text{ on } \Gamma_\epsilon\}.$$

We consider the following problem:
Find $U_\epsilon \in M_\epsilon$ such that, for all $V_\epsilon \in M_\epsilon$,

$$\int_{\Omega_\epsilon} [A_\epsilon \Phi_\epsilon(x, U_\epsilon, B_\epsilon) \nabla U_\epsilon, \nabla(V_\epsilon - U_\epsilon)] \, dx \geq 0 \tag{1}$$

with A_ϵ, B_ϵ, and Φ_ϵ, given functions, M_ϵ a closed, convex, nonempty cone in $\mathcal{V}_\epsilon$.

This problem has applications in Physics. Bruno [1] observed that when a ferromagnet has a thin neck, this will be preferred location for the domain wall. He also noticed that if the geometry of the neck varies rapidly enough, it can influence and even dominate the structure of the wall.

Consider problem (1). We impose the following assumptions:

(A1) The matrix A_ϵ has the following form

$$A_\epsilon(x) = \chi_{\Omega_\epsilon^1}(x) A^1\left(x_1, \frac{x'}{\epsilon}\right) + \chi_{\Omega_\epsilon^0}(x) A^0\left(\frac{x_1}{t_\epsilon}, \frac{x'}{\epsilon r_\epsilon}\right),$$

where $A^1, A^0 \in L^\infty((-1,1) \times S)^{3\times3}$.

(A2) The matrix B_ϵ has the following form

$$B_\epsilon(x) = \chi_{\Omega_\epsilon^1}(x) B^1\left(x_1, \frac{x'}{\epsilon}\right) + \chi_{\Omega_\epsilon^0}(x) B^0\left(\frac{x_1}{t_\epsilon}, \frac{x'}{\epsilon r_\epsilon}\right),$$

where $B^1, B^0 \in L^\infty((-1,1) \times S)^{3\times3}$.

(A3) The functions $\Phi_\epsilon : \Omega_\epsilon \times \mathbb{R} \to \mathbb{R}^{3\times3}$ and $\Psi_\epsilon : \Omega_\epsilon \times \mathbb{R} \to \mathbb{R}^3$ are Carathéodory mappings having the following form:

$$\Phi_\epsilon(x, \eta) = \chi_{\Omega_\epsilon^1}(x) \Phi_\epsilon^1\left(x_1, \frac{x'}{\epsilon}, \eta\right) + \chi_{\Omega_\epsilon^0}(x) \Phi_\epsilon^0\left(\frac{x_1}{t_\epsilon}, \frac{x'}{\epsilon r_\epsilon}, \eta\right);$$

for a.e. $x \in \Omega_\epsilon$, for all $\eta \in \mathbb{R}$;
for all $U_\epsilon \in L^2(\Omega_\epsilon)$, $W_\epsilon \in L^2(\Omega_\epsilon)^3$, $\Phi_\epsilon^1(\cdot, U_\epsilon(\cdot))W_\epsilon(\cdot), \Phi_\epsilon^0(\cdot, U_\epsilon(\cdot))W_\epsilon(\cdot) \in L^2((-1,1) \times S)^3$.

(A4) *Coercivity condition*

There exist $C_1, C_2 > 0$ and $k_1 \in L^\infty(\Omega_\epsilon)$ such that for all $\xi \in \mathbb{R}^3$, $\eta \in \mathbb{R}$

$$[A_\epsilon(x)\Phi_\epsilon(x,\eta)B_\epsilon(x)\xi, \xi] \geq C_1\|\xi\|^2 + C_2|\eta|^{q_1} - k_1(x) \quad \text{a.e. } x \in \Omega_\epsilon \qquad (2)$$

for some $1 < q_1 < 2$, for each $\epsilon > 0$.

(A5) *Growth condition*

There exist $C > 0$ and $\alpha \in L^\infty(\Omega_\epsilon)$ such that for all $\xi \in \mathbb{R}^3$, $\eta \in \mathbb{R}$

$$\|A_\epsilon(x)\Phi_\epsilon(x,\eta)\xi\| \leq C\|\xi\| + C|\eta| + \alpha(x) \quad \text{a.e. } x \in \Omega_\epsilon, \qquad (3)$$

for each $\epsilon > 0$.

(A6) *Monotonicity condition*

For all $\xi, \tau \in \mathbb{R}^n$, $\eta \in \mathbb{R}$,

$$[A_\epsilon(x)\Phi_\epsilon(x,\eta)B_\epsilon(x)\xi - A_\epsilon(x)\Phi_\epsilon(x,\eta)B_\epsilon(x)\tau, \xi - \tau] \geq 0, \quad \text{a. e. } x \in \Omega_\epsilon,$$

for each $\epsilon > 0$.

(A7) If $u_\epsilon \to u$ and $w_\epsilon \rightharpoonup w$ in $L^2(Y^1)$, then

$$\Phi_\epsilon^1(\cdot, u_\epsilon(\cdot))w(\cdot) \to \Phi^1(\cdot, u(\cdot))w(\cdot) \quad \text{strongly in } L^2(Y^1).$$

If $u_\epsilon \to u$ and $w_\epsilon \rightharpoonup w$ in $L^2(Z)$, then

$$\Phi_\epsilon^0(\cdot, u_\epsilon(\cdot))w(\cdot) \to \Phi^0(\cdot, u(\cdot))w(\cdot) \quad \text{strongly in } L^2(Z).$$

3   Asymptotic behavior of the solution

To study the asymptotic behavior we use the change of variables $y = y_\epsilon(x)$ given by

$$y_1 = x_1 \quad y' = \frac{x'}{\epsilon} \qquad (4)$$

which transforms the beam (except the notch) in a cylinder of fixed diameter. This change of variable is classical in the study of asymptotic behavior of variational equalities in thin cylinders or beams (see [6], [12], [14]). We denote by Y_ϵ^-, Y_ϵ^0, Y_ϵ^+, Y_ϵ, and Y_ϵ^S the images of Ω_ϵ^-, Ω_ϵ^0, Ω_ϵ^+, Ω_ϵ, and Ω_ϵ^S by the change of variables $y = y_\epsilon(x)$, i.e.

$$Y_\epsilon^- = (-1, -t_\epsilon) \times S, \quad Y_\epsilon^0 = [-t_\epsilon, t_\epsilon] \times (r_\epsilon S), \quad Y_\epsilon^+ = (t_\epsilon, 1) \times S,$$

$$Y_\epsilon = Y_\epsilon^- \cup Y_\epsilon^0 \cup Y_\epsilon^+, \quad Y_\epsilon^1 = Y_\epsilon^- \cup Y_\epsilon^+.$$

Denote by Y^-, Y^+, and Y^1 the "limits" of Y_ϵ^-, Y_ϵ^+, and Y_ϵ^1, i.e.

$$Y^- = (-1, 0) \times S, \quad Y^+ = (0, 1) \times S, \quad Y^1 = Y^- \cup Y^+.$$

Note that Y_ϵ^1 is contained in its limit Y^1.

The two bases of the beam Γ_ϵ^- and Γ_ϵ^+ are transformed to Λ^- and Λ^+, respectively, where

$$\Lambda^- = \{-1\} \times S \quad \text{and} \quad \Lambda^+ = \{1\} \times S.$$

Γ_ϵ transforms to $\Lambda = \Lambda^- \cup \Lambda^+$.

Let $U_\epsilon \in M_\epsilon$ be the solution of the variational inequality (1). Define $u_\epsilon \in K_\epsilon$ by

$$u_\epsilon(y) = U_\epsilon(y_\epsilon^{-1}(y)) \quad \text{a.e. } y \in Y_\epsilon. \tag{5}$$

K_ϵ being the image of M_ϵ. K_ϵ is a closed, convex, nonempty cone in $\mathcal{D}_\epsilon$, with $\mathcal{D}_\epsilon = \{v \in H^1(Y_\epsilon) \mid v = 0 \text{ on } \Lambda\}$. We need the following two assumptions:

(A8) There exists a nonempty, convex cone K in $H^1(Y^1)$ such that
  (i) $K \cap H^1((-1, 0) \cup (0, 1)) \neq \emptyset$;
  (ii) $\epsilon_i \to 0$, $u_{\epsilon_i} \in K_{\epsilon_i}$, $u \in H^1((-1, 0) \cup (0, 1))$, $u_{\epsilon_i} \rightharpoonup u$ (weakly) in $H^1(Y^1)$ imply $u \in K$.

(A9) There exists a nonempty, convex cone L in $L^2((-1, 1); H^1(S))$ such that
  $\epsilon_i \to 0$, $w_{\epsilon_i} \in K_{\epsilon_i}$, $w \in L^2((-1, 1); H^1(S))$, $w_{\epsilon_i} \rightharpoonup w$ (weakly) in $L^2((-1, 1); H^1(S))$ imply $w \in L$.

By change of variables $y = y_\epsilon(x)$ the operator ∇ transforms to

$$\nabla^\epsilon \cdot = \left(\frac{\partial \cdot}{\partial y_1}, \frac{1}{\epsilon} \frac{\partial \cdot}{\partial y_2}, \frac{1}{\epsilon} \frac{\partial \cdot}{\partial y_3} \right).$$

In the following we recall some results from [11, 4].

Lemma 1 ([11]) *Let $U_\epsilon \in M_\epsilon$ be the solution of the inequality (1) and $u_\epsilon \in K_\epsilon$ given by (5). If assumptions (A1) - (A6) are verified then the sequence U_ϵ satisfies*

$$U_\epsilon \in M_\epsilon, \quad \frac{1}{|\Omega_\epsilon|} \int_{\Omega_\epsilon} |\nabla U_\epsilon|^2 dx \leq C. \tag{6}$$

Theorem 1 ([11]) *Let* U_ϵ *be the solution of the variational inequality (1) and* $u_\epsilon \in K_\epsilon$ *defined by*

$$u_\epsilon(y) = U_\epsilon(y_\epsilon^{-1}(y)) \quad a.e. \ y \in Y_\epsilon.$$

If assumptions (A1)-(A6) and (A8)-(A9) are verified, then there exist three functions u, w, *and* σ^1 *with*

$$u \in H^1((-1,0) \cup (0,1)) \cap K, \quad u(-1) = u(1) = 0,$$

$$w \in L, \quad \sigma^1 \in L^2(Y^1)^3,$$

such that up to extraction of a subsequence

$$\chi_{Y_\epsilon^1} u_\epsilon \to u \quad in \quad L^2(Y^1);$$

$$\chi_{Y_\epsilon^-} \frac{\partial u_\epsilon}{\partial y_1} \rightharpoonup \frac{\partial u}{\partial y_1} \quad in \quad L^2(Y^-);$$

$$\chi_{Y_\epsilon^+} \frac{\partial u_\epsilon}{\partial y_1} \rightharpoonup \frac{\partial u}{\partial y_1} \quad in \quad L^2(Y^+);$$

$$\chi_{Y_\epsilon^1} \frac{1}{\epsilon} \nabla_{y'} u_\epsilon \rightharpoonup \nabla_{y'} w \quad in \quad L^2(Y^1)^2;$$

and

$$\chi_{Y_\epsilon^1} \sigma_\epsilon \rightharpoonup \sigma^1 \quad in \quad L^2(Y^1)^3.$$

Theorem 2 ([11]) *Let* U_ϵ *be the solution of the variational inequality (1) and* $u \in H^1((-1,0) \cup (0,1)) \cap K$ *given in Theorem 1. If assumptions (A1)-(A6) and (A8) are verified, then there exists a subsequence of solutions* U_ϵ, *also denoted by* U_ϵ, *such that*

$$\lim_{\epsilon \to 0} \frac{1}{|\Omega_\epsilon|} \int_{\Omega_\epsilon} |U_\epsilon(x) - u(x_1)|^2 \, dx = 0. \tag{7}$$

Unfortunately, this change of variables doesn't provide information about what happening near the notch. Thus we use another change of variables, which was given in [4]. Consider the case, when

$$\mu < +\infty \quad \text{and} \quad \nu < +\infty.$$

The change of variables $z = z_\epsilon(x)$ is defined as follows

$$
z_1 = \begin{cases}
\begin{cases}
\frac{1}{\epsilon r_\epsilon}(x_1 + t_\epsilon) - \frac{t_\epsilon}{r_\epsilon^2}, & \text{if} \quad -1 \leq x_1 \leq -t_\epsilon, \\
\frac{x_1}{r_\epsilon^2}, & \text{if} \quad -t_\epsilon \leq x_1 \leq t_\epsilon, \quad \text{if } \mu = 0, \\
\frac{1}{\epsilon r_\epsilon}(x_1 - t_\epsilon) + \frac{t_\epsilon}{r_\epsilon^2}, & \text{if} \quad t_\epsilon \leq x_1 \leq 1,
\end{cases} \\
\begin{cases}
\frac{\mu r_\epsilon}{\epsilon t_\epsilon}(x_1 + t_\epsilon) - \mu, & \text{if} \quad -1 \leq x_1 \leq -t_\epsilon, \\
\frac{\mu}{t_\epsilon}x_1, & \text{if} \quad -t_\epsilon \leq x_1 \leq t_\epsilon, \quad \text{if } \mu > 0, \\
\frac{\mu r_\epsilon}{\epsilon t_\epsilon}(x_1 - t_\epsilon) + \mu, & \text{if} \quad t_\epsilon \leq x_1 \leq 1
\end{cases}
\end{cases}
\qquad z' = \frac{x'}{\epsilon r_\epsilon}.
$$

$$(8)$$

This change of variables transforms the notch in a cylinder of fixed diameter and length, but transforms the rest of the beam in a very large domain. But it allows to describe the behavior of the solution U_ϵ of inequality (1) when x_1 is close to zero.

We denote by Z_ϵ^-, Z_ϵ^0, Z_ϵ^+, Z_ϵ, and Z_ϵ^1 the images of Ω_ϵ^-, Ω_ϵ^0, Ω_ϵ^+, Ω_ϵ, and Ω_ϵ^1 by the change of variables $z = z_\epsilon(x)$, i.e.

$$
Z_\epsilon^- = \left(-\frac{1 - t_\epsilon}{\epsilon r_\epsilon} - \frac{t_\epsilon}{r_\epsilon^2}, -\frac{t_\epsilon}{r_\epsilon^2} \right) \times \left(\frac{1}{r_\epsilon}S \right), \quad Z_\epsilon^0 = \left[-\frac{t_\epsilon}{r_\epsilon^2}, \frac{t_\epsilon}{r_\epsilon^2} \right] \times S,
$$

$$
\text{and} \quad Z_\epsilon^+ = \left(\frac{t_\epsilon}{r_\epsilon^2}, \frac{1 - t_\epsilon}{\epsilon r_\epsilon} + \frac{t_\epsilon}{r_\epsilon^2} \right) \times \left(\frac{1}{r_\epsilon}S \right)
$$

if $\mu = 0$, and

$$
Z_\epsilon^- = \left(-\frac{\mu r_\epsilon(1 - t_\epsilon)}{\epsilon t_\epsilon} - \mu, -\mu \right) \times \left(\frac{1}{r_\epsilon}S \right), \quad Z_\epsilon^0 = [-\mu, \mu] \times S,
$$

$$
\text{and } Z_\epsilon^+ = \left(\mu, \frac{\mu r_\epsilon(1 - t_\epsilon)}{\epsilon t_\epsilon} + \mu \right) \times \left(\frac{1}{r_\epsilon}S \right)
$$

if $\mu > 0$. We set

$$
Z_\epsilon = Z_\epsilon^- \cup Z_\epsilon^0 \cup Z_\epsilon^+, \quad Z_\epsilon^1 = Z_\epsilon^- \cup Z_\epsilon^+.
$$

We denote by Z^-, Z^+, and Z^0 the "limits" of Z_ϵ^-, Z_ϵ^+, and Z_ϵ^0, i.e.

$$
Z^- = (-\infty, -\mu) \times \mathbb{R}^2, \quad Z^+ = (\mu, +\infty) \times \mathbb{R}^2, \quad Z^0 = [-\mu, \mu] \times S,
$$

and define

$$
Z = Z^- \cup Z^0 \cup Z^+, \quad Z^1 = Z^- \cup Z^+.
$$

Remark 1 ([4]) *In (8) there are two definitions of z_ϵ corresponding to the cases $\mu = 0$ and $\mu > 0$. Actually when $\mu > 0$, we could define z_ϵ by the definition given for $\mu = 0$ because*

$$\mu \sim \frac{t_\epsilon}{r_\epsilon^2}, \quad \frac{\mu r_\epsilon}{\epsilon t_\epsilon} \sim \frac{1}{\epsilon r_\epsilon}, \quad and \quad \frac{\mu}{t_\epsilon} \sim \frac{1}{r_\epsilon^2}.$$

The definition (8) which distinguishes the cases $\mu = 0$ and $\mu > 0$ has the advantage that the image Z_ϵ of Ω_ϵ by the change of variables $z = z_\epsilon(x)$ is contained in its "limit" Z for every $\epsilon > 0$ and Z_ϵ^0 is fixed for $\mu > 0$; then a function defined in Z has a restriction to Z_ϵ.

Theorem 3 ([4]) *Let $(U_\epsilon)_\epsilon$ be a sequence which satisfies (6). Define $\hat{u}_\epsilon \in H^1(Z_\epsilon)$ by*

$$\hat{u}_\epsilon(z) = U_\epsilon(z_\epsilon^{-1}(z)), \quad a.e. \ z \in Z_\epsilon. \tag{9}$$

Then there exists a function $\hat{u}$, with

$$\hat{u} \in H_{loc}^1(Z), \ \hat{u} - u(0^-) \in L^6(Z^-), \ \hat{u} - u(0^+) \in L^6(Z^+), \ \nabla \hat{u} \in L^2(Z)^3,$$

(where u is defined in Corollary 1), such that for every $R > 0$, up to extraction of a subsequence,

$$\chi_{Z_\epsilon \cap B_3(0,R)} \hat{u}_\epsilon \to \chi_{B_3(0,R)} \hat{u} \quad in \ L^2(Z) \ strongly,$$

$$\chi_{Z_\epsilon} \nabla \hat{u}_\epsilon \rightharpoonup \nabla \hat{u} \quad in \ L^2(Z)^3 \ weakly,$$

where $B_3(0,R)$ denotes the 3-dimensional ball with center (0, 0, 0) and diameter R. Moreover, if $\mu = 0$, then $\hat{u}$ only depends on z_1 and satisfies

$$\hat{u} = u(0^-) \ in \ Z^-, \quad \hat{u} = u(0^+) \ in \ Z^+.$$

If $\nu = \mu = 0$, then $u(0^-) = u(0^+)$.
If $\nu = 0$ and $\mu > 0$, then there exists a function $\hat{w} \in L^2((-\mu, \mu); H^1(S))$ such that up to extraction of a subsequence,

$$\frac{r_\epsilon}{\epsilon} \nabla_{z'} \hat{u}_\epsilon \rightharpoonup \nabla_{z'} \hat{w} \quad in \ L^2(Z^0)^2 \ weakly.$$

Let $\hat{K}_\epsilon$ be the image of M_ϵ by the change of variables $z = z_\epsilon(x)$. $\hat{K}_\epsilon$ is a closed, convex, nonempty cone in $H^1(Z_\epsilon)$. We need the following two assumptions:

(A10) There exists a nonempty subset $\hat{K}$ of $H_{loc}^1(Z)$ such that

$$\epsilon_i \to 0, \ R > 0, \ \hat{u}_{\epsilon_i} \in \hat{K}_{\epsilon_i}, \ \hat{u} \in H^1_{loc}(Z),$$

$$\chi_{Z_\epsilon \cap B_3(0,R)}\hat{u}_{\epsilon_i} \to \chi_{B_3(0,R)}\hat{u} \ \text{ (strongly) in } L^2(Z),$$

and

$$\chi_{Z_\epsilon}\nabla\hat{u}_{\epsilon_i} \rightharpoonup \nabla\hat{u} \ \text{ (weakly) in } (L^2(Z))^3,$$

imply $\hat{u} \in \hat{K}$.

(A11) There exists a nonempty, convex cone $\hat{L}$ in $L^2((-\mu,\mu); H^1(S))$ such that

$$\epsilon_i \to 0, \ \hat{w}_{\epsilon_i} \in K_{\epsilon_i}, \ \hat{w} \in L^2((-\mu,\mu); H^1(S)), \ \hat{w}_{\epsilon_i} \rightharpoonup \hat{w} \text{ (weakly) in}$$
$$L^2((-\mu,\mu); H^1(S)) \text{ imply } \hat{w} \in \hat{L}.$$

Theorem 4 *Let* $U_\epsilon \in M_\epsilon$ *be the solution of the variational inequality (1),* $u \in H^1((-1,0) \cup (0,1)) \cap K$ *defined in Theorem 1, and* $\hat{u}_\epsilon \in \hat{K}_\epsilon$ *given by (9). If assumptions (A1)-(A6) and (A8)-(A11) are verified, then there exists a function* $\hat{u} \in \hat{K}$, *with*

$$\hat{u} - u(0^-) \in L^6(Z^-), \ \hat{u} - u(0^+) \in L^6(Z^+), \ \nabla\hat{u} \in L^2(Z)^3, \tag{10}$$

such that for every $R > 0$, *up to extraction of a subsequence,*

$$\chi_{Z_\epsilon \cap B_3(0,R)}\hat{u}_\epsilon \to \chi_{B_3(0,R)}\hat{u} \quad \text{in } L^2(Z) \text{ strongly,}$$

$$\chi_{Z_\epsilon}\nabla\hat{u}_\epsilon \rightharpoonup \nabla\hat{u} \quad \text{in } L^2(Z)^3 \text{ weakly.}$$

Moreover, if $\mu = 0$, *then* $\hat{u}$ *only depends on* z_1 *and satisfies*

$$\hat{u} = u(0^-) \quad \text{in } Z^-, \quad \hat{u} = u(0^+) \quad \text{in } Z^+.$$

If $\nu = \mu = 0$, *then* $u(0^-) = u(0^+)$.
If $\nu = 0$ *and* $\mu > 0$, *then there exists a function* $\hat{w} \in \hat{L}$ *such that up to extraction of a subsequence,*

$$\frac{r_\epsilon}{\epsilon}\nabla_{z'}\hat{u}_\epsilon \rightharpoonup \nabla_{z'}\hat{w} \quad \text{in } L^2(Z^0)^2 \text{ weakly.} \tag{11}$$

Proof. From Lemma 1 it follows that there exists a subsequence of solutions U_ϵ, also denoted by U_ϵ, such that (6) is satisfied. Thus by Theorem 3 we get that there exists a function $\hat{u} \in H^1_{loc}(Z)$ such that the statement of the theorem is true. By assumption (A10) we get that $\hat{u} \in \hat{K}$.

If $\nu = 0$ and $\mu > 0$ then, by Theorem 3, there exists a function $\hat{w} \in L^2((-\mu,\mu); H^1(S))$ such that up to extraction of a subsequence, (11) holds. Then by assumption (A11) we get that $\hat{w} \in \hat{L}$. ∎

Lemma 2 *Let U_ϵ be one solution of the variational inequality (1), $\hat{u}_\epsilon$ defined by (8). Assume that (A1)-(A3) and (A5) hold. Then*

$$\left\| A^0\left(\frac{\cdot}{\mu},\cdot\right) \Phi_\epsilon^0\left(\frac{\cdot}{\mu},\cdot,\hat{u}_\epsilon(\cdot)\right) B^0\left(\frac{\cdot}{\mu},\cdot\right) \nabla\hat{u}_\epsilon(\cdot) \right\|_{L^2(Z^0)}$$

is bounded.

Proof. Taking the square of the first growth condition from (A5), multiplying by $\frac{1}{\epsilon^2}$, and integrating on Ω_ϵ^0, we obtain

$$\frac{1}{\epsilon^2}\int_{\Omega_\epsilon^0} \|A_\epsilon(x)\Phi(x,U_\epsilon(x))B_\epsilon(x)\nabla U_\epsilon(x)\|^2 \, dx \leq$$

$$\leq \frac{1}{\epsilon^2}\int_{\Omega_\epsilon^0} \|\nabla U_\epsilon(x)\|^2 \, dx + \frac{1}{\epsilon^2}\int_{\Omega_\epsilon^0} |U_\epsilon(x)|^2 \, dx + \frac{|\Omega_\epsilon^0|}{\epsilon^2}\|\alpha\|_\infty.$$

Applying the change of variable z_ϵ and taking out $\frac{1}{r_\epsilon^2}$ from $\hat{\nabla}^\epsilon\hat{u}_\epsilon$, we get

$$\int_{Z^0} \left\| A^0\left(\frac{z_1}{\mu},z'\right) \Phi_\epsilon^0\left(\frac{z_1}{\mu},z',\hat{u}_\epsilon(z)\right) B^0\left(\frac{z_1}{\mu},z'\right) \nabla\hat{u}_\epsilon(z) \right\|^2 \, dz \leq$$

$$\leq C\int_{Z^0} \left\| \left(\frac{\partial\hat{u}_\epsilon(z)}{\partial z_1}, \frac{r_\epsilon}{\epsilon}\frac{\partial\hat{u}_\epsilon(z)}{\partial z_2}, \frac{r_\epsilon}{\epsilon}\frac{\partial\hat{u}_\epsilon(z)}{\partial z_3}\right) \right\|^2 \, dz + r_\epsilon^4 C\int_{Z^0} |\hat{u}_\epsilon(z)|^2 \, dz + \bar{\alpha}.$$

By Theorem 3, $\|\nabla\hat{u}_\epsilon\|_{L^2(Z^0)^3}$ and $\|\hat{u}_\epsilon\|_{L^2(Z^0)}$ are bounded, thus the statement of the lemma holds. ∎

Corollary 1 *Suppose that the assumptions of Lemma 2 are verified. Then there exists $\sigma^0 \in L^2(Z^0)$ such that*

$$A^0\left(\frac{\cdot}{\mu},\cdot\right) \Phi_\epsilon^0\left(\frac{\cdot}{\mu},\cdot,\hat{u}_\epsilon(\cdot)\right) B^0\left(\frac{\cdot}{\mu},\cdot\right) \nabla\hat{u}_\epsilon(\cdot) \rightharpoonup \sigma^0 \quad in \ L^2(Z^0).$$

4 The limit variational inequality

In this section we obtain the limit problem in two cases: when $0 < \mu < +\infty$ and $\nu = 0$ respectively when $\mu = +\infty$ and $0 < \nu < +\infty$. In these cases

$$\frac{\epsilon r_\epsilon}{t_\epsilon} = \frac{\epsilon}{r_\epsilon}\cdot\frac{r_\epsilon^2}{t_\epsilon} \to \frac{\nu}{\mu} = 0,$$

thus the beam has a thin neck.

4.1 The case $0 < \mu < \infty$ and $\nu = 0$

Theorem 5 *Let $0 < \mu < \infty$ and $\nu = 0$.*

Assume that (A1)-(A11) are verified and the following four conditions are satisfied:

(C1) $\varphi \in K$ *implies* $\chi_{Y_\epsilon^1} \varphi \in K_\epsilon$;

(C2) $\psi \in L$ *implies* $\chi_{Y_\epsilon^1} \psi \in K_\epsilon$;

(C3) $\hat{\varphi} \in \hat{K}$ *implies* $\chi_{Z_\epsilon^0} \hat{\varphi} \in \hat{K}_\epsilon$;

(C4) $\hat{\psi} \in \hat{L}$ *implies* $\chi_{Z_\epsilon^0} \hat{\psi} \in \hat{K}_\epsilon$.

Then the following three statements hold:

1) There exists a subsequence of the sequence U_ϵ of solutions of (1), also denoted by U_ϵ, and a function $u \in H^1((-1,0) \cup (0,1)) \cap K$ such that (7) is satisfied.

2) Let u and w be as given in Theorem 1 and $\hat{u}$ and $\hat{w}$ as in Theorem 4. Then $(u, w, \hat{u}, \hat{w})$ solves the limit variational problem:
find $u \in H^1((-1,0) \cup (0,1)) \cap K$, $u(-1) = u(1) = 0$, $w \in L$, and $\hat{u} \in \hat{K}$, $\hat{u}(-\mu) = u(0^-)$, $\hat{u}(\mu) = u(0^+)$, $\hat{w} \in \hat{L}$ such that for all $v \in H^1((-1,0) \cup (0,1)) \cap K$, $v(-1) = v(1) = 0$, $h \in L$, and $\hat{v} \in \hat{K}$, $\hat{v}(-\mu) = v(0^-)$, $\hat{v}(\mu) = v(0^+)$, $\hat{h} \in \hat{L}$,

$$\int_{Y^1} [A^1(y)\Phi^1(y, u(y_1))B^1(y)\nabla'(u,w)(y), \nabla'(v,h)(y) - \nabla'(u,w)(y)] \quad (12)$$
$$+ \int_{Z^0} \left[A^0\left(\frac{z_1}{\mu}, z'\right) \Phi^0\left(\frac{z_1}{\mu}, z', \hat{u}(z)\right) B^0\left(\frac{z_1}{\mu}, z'\right) \nabla'(\hat{u}, \hat{w})(z), \right.$$
$$\left. \nabla'(\hat{v}, \hat{h})(z) - \nabla'(\hat{u}, \hat{w})(z) \right] \, dz \geq 0.$$

3) Let σ^1 be as given in Theorem 1, σ^0 as given in Corollary 1. Then

$$\sigma^1(y) = A^1(y)\Phi^1(y, u(y))B^1(y)\nabla'(u,w)(y) \quad \text{for a.e. } y \in Y^1,$$

$$\sigma^0(z) = A^0\left(\frac{z_1}{\mu}, z'\right) \Phi^0\left(\frac{z_1}{\mu}, z', \hat{u}(z)\right) B^0\left(\frac{z_1}{\mu}, z'\right) \nabla'\left(\hat{u}, \frac{1}{\nu}\hat{u}\right)$$

for a.e. $z \in Z^0$.

Proof. Statement 1) follows from Theorem 2.

2) Since $\nu = 0$, from Theorem 4 it follows that $\hat{u} \in \hat{K}$ only depends on z_1 with

$$\hat{u} = u(0^-) \text{ in } Z^-, \quad \hat{u} = u(0^+) \text{ in } Z^+,$$

and there exists a function $\hat{w} \in \hat{L}$ such that up to extraction of a subsequence,

$$\frac{r_\epsilon}{\epsilon} \nabla_{z'} \hat{u}_\epsilon \rightharpoonup \nabla_{z'} \hat{w} \quad \text{in } L^2(Z^0)^2 \text{ weakly.}$$

Let $\varphi^- \in H^1([-1,0])$ and $\varphi^+ \in H^1([0,1])$ and define $\varphi \in H^1((-1,0) \cup (0,1)) \cap K$ such that

$$\varphi(x_1) = \begin{cases} \varphi^-(x_1), & \text{if } x_1 \in (-1,0) \\ \varphi^+(x_1), & \text{if } x_1 \in (0,1). \end{cases}$$

Let $\psi \in L$, $\hat{\varphi} \in \hat{K}$, and $\hat{\psi} \in \hat{L}$. For ϵ small enough, the sequence V_ϵ defined by

$$V_\epsilon(x) = \chi_{\Omega_\epsilon^1}(x) \left(\varphi(x_1) + \epsilon \psi \left(x_1, \frac{x'}{\epsilon} \right) \right) +$$
$$+ \chi_{\Omega_\epsilon^0}(x) \left(\hat{\varphi} \left(\frac{\mu x_1}{t_\epsilon} \right) + \frac{\epsilon}{r_\epsilon} \hat{\psi} \left(\frac{\mu x_1}{t_\epsilon}, \frac{x'}{\epsilon r_\epsilon} \right) \right), \quad \text{a.e. } x \in \Omega_\epsilon$$

belongs to M_ϵ.

Putting $\eta = U_\epsilon(x)$, $\xi = \nabla U_\epsilon(x)$ and

$$\tau = \tau_\epsilon(x) = \chi_{\Omega_\epsilon^1}(x)(\nabla'(\varphi, \psi) + \lambda f_1)(y_\epsilon(x)) +$$
$$+ \chi_{\Omega_\epsilon^0}(x) \frac{1}{r_\epsilon^2} (\nabla'(\hat{\varphi}, \hat{\psi}) + \lambda f_2)(z_\epsilon(x)), \quad \text{a.e. } x \in \Omega_\epsilon$$

in the monotonicity condition, we get

$$0 \leq \frac{1}{\epsilon^2} \int_{\Omega_\epsilon} [A_\epsilon(x)\Phi_\epsilon(x, U_\epsilon(x))B_\epsilon(x)\nabla U_\epsilon(x) - A_\epsilon(x)\Phi_\epsilon(x, U_\epsilon(x))B_\epsilon(x)\tau_\epsilon(x),$$
$$\nabla U_\epsilon(x) - \tau_\epsilon(x)] \, dx =$$
$$= \frac{1}{\epsilon^2} \int_{\Omega_\epsilon} [A_\epsilon(x)\Phi_\epsilon(x, U_\epsilon(x))B_\epsilon(x)\nabla U_\epsilon(x), \nabla U_\epsilon(x)] \, dx -$$
$$- \frac{1}{\epsilon^2} \int_{\Omega_\epsilon} [A_\epsilon(x)\Phi_\epsilon(x, U_\epsilon(x))B_\epsilon(x)\nabla U_\epsilon(x), \tau_\epsilon(x)] \, dx +$$
$$- \frac{1}{\epsilon^2} \int_{\Omega_\epsilon} [A_\epsilon(x)\Phi_\epsilon(x, U_\epsilon(x))B_\epsilon(x)\tau_\epsilon(x), \nabla U_\epsilon(x)] \, dx -$$
$$+ \frac{1}{\epsilon^2} \int_{\Omega_\epsilon} [A_\epsilon(x)\Phi_\epsilon(x, U_\epsilon(x))B_\epsilon(x)\tau_\epsilon(x), \tau_\epsilon(x)] \, dx =$$
$$= T_1^\epsilon - T_2^\epsilon - T_3^\epsilon + T_4^\epsilon.$$

In the following we study each term separately. The first term

$$
\begin{aligned}
T_1^\epsilon \;=\;& \frac{1}{\epsilon^2}\int_{\Omega_\epsilon}\left[A_\epsilon(x)\Phi_\epsilon(x,U_\epsilon(x))B_\epsilon(x)\nabla U_\epsilon(x),\nabla U_\epsilon(x)\right]\,dx \;\leq\\
\leq\;& \frac{1}{\epsilon^2}\int_{\Omega_\epsilon}\left[A_\epsilon(x)\Phi_\epsilon(x,U_\epsilon(x))B_\epsilon(x)\nabla U_\epsilon(x),\nabla V_\epsilon(x)\right]\,dx\\
=\;& \frac{1}{\epsilon^2}\int_{\Omega_\epsilon^1}\left[A_\epsilon^1(y_\epsilon(x))\Phi_\epsilon^1(y_\epsilon(x),U_\epsilon(x))B_\epsilon^1(y_\epsilon(x))\nabla U_\epsilon(x),\right.\\
& \left.\left(\frac{d\varphi(x_1)}{dx_1}+\epsilon\frac{\partial\psi(y_\epsilon(x))}{\partial x_1},\frac{\partial\psi(y_\epsilon(x))}{\partial x_2},\frac{\partial\psi(y_\epsilon(x))}{\partial x_3}\right)\right]\,dx +\\
& +\frac{1}{\epsilon^2}\int_{\Omega_\epsilon^0}\left[A_\epsilon^0(z_\epsilon(x))\Phi_\epsilon^0(z_\epsilon(x),U_\epsilon(x))B_\epsilon^0(z_\epsilon(x))\nabla U_\epsilon(x),\right.\\
& \left.\left(\frac{\mu}{t_\epsilon}\frac{\partial\hat\varphi\left(\frac{\mu x_1}{t_\epsilon}\right)}{\partial x_1}+\frac{\epsilon\mu}{r_\epsilon t_\epsilon}\frac{\partial\hat\psi(z_\epsilon(x))}{\partial x_1},\frac{1}{r_\epsilon^2}\frac{\partial\hat\psi(z_\epsilon(x))}{\partial x_2},\frac{1}{r_\epsilon^2}\frac{\partial\hat\psi(z_\epsilon(x))}{\partial x_3}\right)\right]\,dx
\end{aligned}
$$

(using the change of variable $y=y_\epsilon(x)$ in the integral over Ω_ϵ^1 and the change of variables $z=z_\epsilon(x)$ in the integral over Ω_ϵ^0)

$$
\begin{aligned}
=\;& \int_{Y_\epsilon^1}\left[A^1(y)\Phi_\epsilon^1(y,u_\epsilon(y))B^1(y)\nabla^\epsilon u_\epsilon(y),\right.\\
& \left.\left(\frac{d\varphi(y_1)}{dy_1}+\epsilon\frac{\partial\psi(y)}{\partial y_1},\frac{\partial\psi(y)}{\partial y_2},\frac{\partial\psi(y)}{\partial y_3}\right)\right]\,dy+\\
& +\frac{1}{\mu}t_\epsilon r_\epsilon^2\int_{Z^0}\left[A^0\left(\frac{z_1}{\mu},z'\right)\Phi_\epsilon^0\left(\frac{z_1}{\mu},z',\hat u(z)\right)B^0\left(\frac{z_1}{\mu},z'\right)\cdot\right.\\
& \cdot\left(\frac{\mu}{t_\epsilon}\frac{\partial\hat u_\epsilon(z)}{\partial z_1},\frac{1}{\epsilon r_\epsilon}\frac{\partial\hat u_\epsilon(z)}{\partial z_2},\frac{1}{\epsilon r_\epsilon}\frac{\partial\hat u_\epsilon(z)}{\partial z_3}\right),\\
& \left.\left(\frac{\mu}{t_\epsilon}\frac{d\hat\varphi(z_1)}{dz_1}+\frac{\epsilon}{r_\epsilon t_\epsilon}\frac{\partial\hat\psi(z)}{\partial z_1},\frac{1}{r_\epsilon^2}\frac{\partial\hat\psi(z)}{\partial z_2},\frac{1}{r_\epsilon^2}\frac{\partial\hat\psi(z)}{\partial z_3}\right)\right]\,dz
\end{aligned}
$$

Taking the limit, we get

$$
T_1^\epsilon \to \int_{Y^1}\left[\sigma^1(y),\nabla'(\varphi,\psi)(y)\right]\,dy + \int_{Z^0}\left[\sigma^0(z),\nabla'(\hat\varphi,\hat\psi)(z)\right]\,dz.
$$

The second term

$$T_2^\epsilon = \frac{1}{\epsilon^2} \int_{\Omega_\epsilon} [A_\epsilon(x)\Phi_\epsilon(x, U_\epsilon(x))B_\epsilon(x)\nabla U_\epsilon(x), \tau_\epsilon(x)] \; dx \rightarrow$$

$$\rightarrow \int_{Y^1} \left[\sigma^1(y), (\nabla'(\varphi, \psi) + \lambda f_1)(y) \right] \; dy +$$

$$+ \int_{Z^0} \left[\sigma^0(z), (\nabla'(\hat{\varphi}, \hat{\psi}) + \lambda f_2)(z) \right] \; dz,$$

when ϵ tends to zero.

The third term

$$T_3^\epsilon = \frac{1}{\epsilon^2} \int_{\Omega_\epsilon} [A_\epsilon(x)\Phi_\epsilon(x, U_\epsilon(x))B_\epsilon(x)\tau_\epsilon(x), \nabla U_\epsilon(x)] \; dx \rightarrow$$

$$\rightarrow \int_{Y^1} \left[A^1(y)\Phi^1(y, u(y))B^1(y)(\nabla'(\varphi, \psi) + \lambda f_1)(y), \nabla'(u, w)(y) \right] \; dy +$$

$$+ \int_{Z^0} \left[A^0\left(\frac{z_1}{\mu}, z'\right) \Phi^0\left(\frac{z_1}{\mu}, z', \hat{u}(z)\right) B^0\left(\frac{z_1}{\mu}, z'\right) (\nabla'(\hat{\varphi}, \hat{\psi}) + \lambda f_2)(z), \right.$$
$$\left. \nabla'(\hat{u}, \hat{w})(z), \right] \; dz,$$

when ϵ tends to zero.

The last term

$$T_4^\epsilon = \frac{1}{\epsilon^2} \int_{\Omega_\epsilon} [A_\epsilon(x)\Phi_\epsilon(x, U_\epsilon(x))B_\epsilon(x)\tau_\epsilon(x), \tau_\epsilon(x)] \; dx \rightarrow$$

$$\rightarrow \int_{Y^1} \left[A^1(y)\Phi^1(y, u(y))B^1(y)(\nabla'(\varphi, \psi) + \lambda f_1)(y), \right.$$
$$\left. (\nabla'(\varphi, \psi) + \lambda f_1)(y) \right] \; dy +$$

$$+ \int_{Z^0} \left[A^0\left(\frac{z_1}{\mu}, z'\right) \Phi^0\left(\frac{z_1}{\mu}, z', \hat{u}(z)\right) B^0\left(\frac{z_1}{\mu}, z'\right) (\nabla'(\hat{\varphi}, \hat{\psi}) + \lambda f_2)(z), \right.$$
$$\left. (\nabla'(\hat{\varphi}, \hat{\psi}) + \lambda f_2)(z) \right] \; dz,$$

when ϵ tends to zero.

Adding the limits of T_1^ϵ, T_2^ϵ, T_3^ϵ, and T_4^ϵ, we get

$$-\int_{Y^1} [\sigma^1(y), \lambda f_1(y)] \; dy - \int_{Z^0} [\sigma^0(z), \lambda f_2(z)] \; dz + \tag{13}$$

$$+ \int_{Y^1} [A^1(y)\Phi^1(y, u(y_1))B^1(y)(\nabla'(\varphi, \psi) + \lambda f_1)(y), \nabla'(\varphi, \psi)(y) -$$

$$- \nabla'(u, w)(y) + \lambda f_1(y)] +$$

$$+ \int_{Z^0} \left[A^0 \left(\frac{z_1}{\mu}, z' \right) \Phi^0 \left(\frac{z_1}{\mu}, z', \hat{u}(z) \right) B^0 \left(\frac{z_1}{\mu}, z' \right) (\nabla'(\hat{\varphi}, \hat{\psi}) + \lambda f_2)(z), \right.$$

$$\left. \nabla'(\hat{\varphi}, \hat{\psi})(z) - \nabla'(\hat{u}, \hat{w})(z) + \lambda f_2(z), \right] \; dz \geq 0.$$

Setting

$$\varphi - u = \theta(v - u), \quad \psi - w = \theta(h - w), \quad \hat{\varphi} = \theta \hat{v}, \quad \text{and} \quad \hat{\psi} = \theta \hat{h},$$

where $\theta > 0$, dividing by θ, then letting $\theta \to 0$, we get the limit variational inequality.

Putting

$$(\varphi, u) = (\psi, w) \quad \text{and} \quad (\hat{\varphi}, \hat{u}) = (\hat{\psi}, \hat{w}),$$

dividing by λ, and letting $\lambda \to 0$, we get

$$\int_{Y^1} [\sigma^1(y) - A^1(y)\Phi^1(y, u(y_1))B^1(y)\nabla'(u, w)(y), f_1(y)] \; dy +$$

$$+ \int_{Z^0} \left[\sigma^0(z) - A^0 \left(\frac{z_1}{\mu}, z' \right) \Phi^0 \left(\frac{z_1}{\mu}, z', \hat{u}(z) \right) B^0 \left(\frac{z_1}{\mu}, z' \right) \nabla'(\hat{u}, \hat{w})(z), \right.$$

$$\left. f_2(z) \right] \; dz \geq 0, \quad \forall f_1 \in H^1(Y^1), \forall f_2 \in H^1(Z).$$

Then 3) follows. ∎

4.2 The case $\mu = +\infty$ and $0 < \nu < +\infty$

Theorem 6 *Let $\mu = +\infty$ and $0 < \nu < +\infty$. Assume that (A1)-(A9) are verified and the following two conditions are satisfied:*

(C1) $\varphi \in K$ *implies* $\chi_{Y^1_\epsilon} \varphi \in K_\epsilon$;

(C2) $\psi \in L$ *implies* $\chi_{Y^1_\epsilon} \psi \in K_\epsilon$.

Then the following three statements hold:

1) There exists a subsequence of the sequence U_ϵ of solutions of (1), also denoted by U_ϵ, and a function $u \in H^1((-1, 0) \cup (0, 1)) \cap K$ such that (7) is satisfied.

2) Let u and w be given as in Theorem 1. Then (u, w) solves the limit variational problem:
find $u \in H^1((-1, 0) \cup (0, 1)) \cap K$, $u(-1) = u(1) = 0$ and $w \in L$ such that for all $v \in H^1((-1, 0) \cup (0, 1)) \cap K$, $v(-1) = v(1) = 0$ and $h \in L$

$$\int_{Y^1} [A^1(y)\Phi^1(y, u(y_1))B^1(y)\nabla'(u, w)(y), \nabla'(v, h)(y) - \nabla'(u, w)(y)] \geq 0.$$

$$(14)$$

3) Let σ^1 given in Theorem 1. Then

$$\sigma^1(y) = A^1(y)\Phi^1(y, u(y))B^1(y)\nabla'(u, w)(y) \quad \text{for a.e. } y \in Y^1.$$

Proof. Statement 1) follows from Theorem 2.

To prove statement 2), let $\varphi^- \in H^1([-1, 0])$ and $\varphi^+ \in H^1([0, 1])$ and define $\varphi \in H^1((-1, 0) \cup (0, 1)) \cap K$ such that

$$\varphi(x_1) = \begin{cases} \varphi^-(x_1), & \text{if } x_1 \in (-1, 0) \\ \varphi^+(x_1), & \text{if } x_1 \in (0, 1). \end{cases}$$

Let $\psi \in L$ and $\gamma^0 : [0, +\infty) \to \mathbb{R}$ defined by

$$\gamma^0(\tau) = \begin{cases} \tau, & \text{if } 0 \le \tau \le 1 \\ 1, & \text{if } \tau \ge 1. \end{cases}$$

and

$$V_\epsilon(x) = \varphi(x_1)\gamma^0\left(\frac{|x_1|}{t_\epsilon}\right) + \epsilon\psi\left(x_1, \frac{x'}{\epsilon}\right), \quad \text{a.e } \in \Omega_\epsilon,$$

which belongs to M_ϵ.

For ϵ small enough, by a simple calculation we obtain

$$\frac{1}{\epsilon^2}\int_{\Omega_\epsilon^1}\left|\nabla V_\epsilon - \frac{d\varphi(x_1)}{dx_1}e_1 - \nabla_{y'}\psi\left(x_1, \frac{x'}{\epsilon}\right)\right| \, dx + \frac{1}{\epsilon^2}\int_{\Omega_\epsilon^0}|\nabla V_\epsilon| \, dx \le$$

$$\le C\left(\epsilon^2 + \frac{r_\epsilon^2}{t_\epsilon}\right)$$

which tends to zero since $\mu = +\infty$.

Putting $\eta = U_\epsilon(x)$, $\xi = \nabla U_\epsilon(x)$ and

$$\tau = \tau_\epsilon(x) = \begin{cases} (\nabla'(\varphi, \psi) + \lambda f_1)(y_\epsilon(x)), & \text{if } x \in \Omega_\epsilon^1 \\ 0, & \text{if } x \in \Omega_\epsilon^0 \end{cases}$$

in the monotonicity condition, we get

$$
\begin{aligned}
0 \leq \frac{1}{\epsilon^2} \int_{\Omega_\epsilon} & [A_\epsilon(x)\Phi_\epsilon(x, U_\epsilon(x))B_\epsilon(x)\nabla U_\epsilon(x) - A_\epsilon(x)\Phi_\epsilon(x, U_\epsilon(x))B_\epsilon(x)\tau_\epsilon(x), \\
& \nabla U_\epsilon(x) - \tau_\epsilon(x)] \ dx = \\
= \frac{1}{\epsilon^2} \int_{\Omega_\epsilon} & [A_\epsilon(x)\Phi_\epsilon(x, U_\epsilon(x))B_\epsilon(x)\nabla U_\epsilon(x), \nabla U_\epsilon(x)] \ dx- \\
- \frac{1}{\epsilon^2} \int_{\Omega_\epsilon} & [A_\epsilon(x)\Phi_\epsilon(x, U_\epsilon(x))B_\epsilon(x)\nabla U_\epsilon(x), \tau_\epsilon(x)] \ dx- \\
- \frac{1}{\epsilon^2} \int_{\Omega_\epsilon} & [A_\epsilon(x)\Phi_\epsilon(x, U_\epsilon(x))B_\epsilon(x)\tau_\epsilon(x), \nabla U_\epsilon(x)] \ dx+ \\
+ \frac{1}{\epsilon^2} \int_{\Omega_\epsilon} & [A_\epsilon(x)\Phi_\epsilon(x, U_\epsilon(x))B_\epsilon(x)\tau_\epsilon(x), \tau_\epsilon(x)] \ dx = \\
= T_1^\epsilon - T_2^\epsilon & - T_3^\epsilon + T_4^\epsilon.
\end{aligned}
$$

In the following we study each term separately. The first term

$$
\begin{aligned}
T_1^\epsilon = \frac{1}{\epsilon^2} \int_{\Omega_\epsilon} & [A_\epsilon(x)\Phi_\epsilon(x, U_\epsilon(x))B_\epsilon(x)\nabla U_\epsilon(x), \nabla U_\epsilon(x)] \ dx \leq \\
\leq \frac{1}{\epsilon^2} \int_{\Omega_\epsilon} & [A_\epsilon(x)\Phi_\epsilon(x, U_\epsilon(x))B_\epsilon(x)\nabla U_\epsilon(x), \nabla V_\epsilon(x)] \ dx = \\
= \frac{1}{\epsilon^2} \int_{\Omega_\epsilon^1} & [A_\epsilon(x)\Phi_\epsilon(x, U_\epsilon(x))B_\epsilon(x)\nabla U_\epsilon(x), \nabla V_\epsilon(x)] \ dx+ \\
+ \frac{1}{\epsilon^2} \int_{\Omega_\epsilon^0} & [A_\epsilon(x)\Phi_\epsilon(x, U_\epsilon(x))B_\epsilon(x)\nabla U_\epsilon(x), \nabla V_\epsilon(x)] \ dx,
\end{aligned}
$$

where the second term tends to zero. We use the change of variables $y = y_\epsilon(x)$ in the first term:

$$
\begin{aligned}
T_1^\epsilon \leq \int_{Y_\epsilon^1} & \Big[A^1(y)\Phi_\epsilon^1(y, u_\epsilon(y))B^1(y)\nabla^\epsilon u_\epsilon(y), \\
& \left(\frac{d\varphi(y_1)}{dy_1} + \epsilon \frac{\partial\psi(y)}{\partial y_1}, \frac{\partial\psi(y)}{\partial y_2}, \frac{\partial\psi(y)}{\partial y_3} \right) \Big] \ dy + O_\epsilon =
\end{aligned}
$$

$$= \int_{Y^1} \Big[A^1(y)\Phi^1_\epsilon(y, u_\epsilon(y))B^1(y)\nabla^\epsilon u_\epsilon(y),$$
$$\left(\frac{d\varphi(y_1)}{dy_1} + \epsilon\frac{\partial\psi(y)}{\partial y_1}, \frac{\partial\psi(y)}{\partial y_2}, \frac{\partial\psi(y)}{\partial y_3} \right) \Big] \; dy + O_\epsilon.$$

Taking the limit of both sides, we get

$$\lim_{\epsilon \to 0} T^\epsilon_1 \le \int_{Y^1} \Big[\sigma^1(y), \nabla'(\varphi, \psi)(y) \Big] \; dy.$$

The third term

$$T^\epsilon_3 = \frac{1}{\epsilon^2}\int_{\Omega_\epsilon} [A_\epsilon(x)\Phi_\epsilon(x, U_\epsilon(x))B_\epsilon(x)\tau_\epsilon(x), \nabla U_\epsilon(x)] \; dx =$$
$$= \frac{1}{\epsilon^2}\int_{\Omega^1_\epsilon} \Big[A^1(y_\epsilon(x))\Phi_\epsilon(y_\epsilon(x), U_\epsilon(x))B^1(y_\epsilon(x))(\nabla'(\varphi, \psi) + \lambda f_1)(y_\epsilon(x)),$$
$$\nabla U_\epsilon(x)] \; dx,$$

as the integral on Ω^0_ϵ is equal with zero because $\tau_\epsilon = 0$ on Ω^0_ϵ. Using the change of variable $y = y_\epsilon(x)$ we get

$$T^\epsilon_3 = \int_{Y^1_\epsilon} \Big[A^1(y)\Phi_\epsilon(y, u_\epsilon(y))B^1(y)(\nabla'(\varphi, \psi) + \lambda f)(y), \nabla^\epsilon u_\epsilon(y) \Big] \; dy =$$
$$= \int_{Y^1} \Big[A^1(y)\Phi_\epsilon(y, u_\epsilon(y))B^1(y)(\nabla'(\varphi, \psi) + \lambda f_1)(y), \nabla^\epsilon u_\epsilon(y) \Big] \; dy + O_\epsilon.$$

Taking the limit when $\epsilon \to 0$, we get

$$T^\epsilon_3 \to \int_{Y^1} \Big[A^1(y)\Phi(y, u(y_1))B^1(y)(\nabla'(\varphi, \psi) + \lambda f_1)(y), \nabla'(u, w)(y) \Big] \; dy.$$

Similarly

$$T^\epsilon_2 \to \int_{Y^1} \Big[\sigma^1(y), (\nabla'(\varphi, \psi) + \lambda f_1)(y) \Big] \; dy$$

and

$$T^\epsilon_4 \to \int_{Y^1} \Big[A^1(y)\Phi(y, u(y_1))B^1(y)(\nabla'(\varphi, \psi) + \lambda f_1)(y),$$
$$(\nabla'(\varphi, \psi) + \lambda f_1)(y) \Big] \; dy,$$

when $\epsilon \to 0$.

Adding the limits of T_1^ϵ, T_2^ϵ, T_3^ϵ, and T_4^ϵ, we get

$$\int_{Y^1} [A^1(y)\Phi^1(y, u(y_1))B^1(y)(\nabla'(\varphi, \psi) + \lambda f_1)(y), \nabla'(\varphi, \psi)(y)- \qquad (15)$$

$$-\nabla'(u, w)(y) + \lambda f_1(y)] \, dz - \int_{Y^1} [\sigma^1(y), \lambda f_1(y)] \, dy \geq 0.$$

Setting
$$\varphi - u = \theta(v - u), \quad \text{and} \quad \psi - w = \theta(h - w),$$

where $\theta > 0$, dividing by θ, then letting $\theta \to 0$, we get the limit variational inequality.

3) Putting
$$(\varphi, u) = (\psi, w),$$

dividing by λ, and letting $\lambda \to 0$, we get

$$\int_{Y^1} [\sigma^1(y) - A^1(y)\Phi^1(y, u(y_1))B^1(y)\nabla'(u, w)(y), f_1(y)] \, dy \geq 0$$
$$\forall f_1 \in H^1(Y^1).$$

Then 3) follows. ∎

Acknowledgement

References

[1] P. Bruno, Geometrically constrained magnetic wall, *Phys. Rev. Lett.*, **83** (1999), 2425–2428.

[2] E. Cabib, L. Freddi, A. Morassi, D. Percivale, Thin notched beams, *J. Elasticity*, **64** (2002), 157–178.

[3] J. Casado-Díaz, M. Luna-Laynez, F. Murat, Asymptotic behavior of diffusion problems in a domain made of two cylinders of different diameters and lengths, *C. R. Acad. Sci. Paris, Sér. I*, **338** (2004), 133–138.

[4] J. Casado-Díaz, M. Luna-Laynez, F. Murat, The diffusion equation in a notched beam, *Calculus of Variations*, **31** (2008), 297–323.

[5] P. Courilleau, J. Mossino, Compensated compactness for nonlinear homogenization and reduction of dimension, *Calculus of Variations*, **20** (2004), 65–91.

[6] B. Gustafsson, J. Mossino, Non-periodic explicit homogenization and reduction of dimension: the linear case, *IMA Journal of Applied Mathematics* **68** (2003), 269–298.

[7] J. K. Hale, J. Vegas, A nonlinear parabolic equation with varying domain, *Arch. Rat. Mech. Anal.*, **86** (1984), 99–123.

[8] S. Jimbo, Singular perturbation of domains and semilinear elliptic equation, *J. Fac. Sci. Univ. Tokyo*, **35** (1988), 27–76.

[9] S. Jimbo, Singular perturbation of domains and semilinear elliptic equation 2, *J. Diff. Equat.*, **75** (1988), 264–289.

[10] R. V. Kohn, V. V. Slastikov, Geometrically constrained walls, *Calculus of Variations and Partial Differential Equations*, **28** (2007), 33–57.

[11] I. Marchis, Asymptotic behavior of the solution of nonlinear parametric variational inequalities in notched beams, accepted in *Studia Universitatis Babeş-Bolyai, Mathematica*.

[12] F. Murat, A. Sili, Problèmes monotones dans des cylindres de faible diamètre formés de matériaux hétérogènes, *C. R. Acad. Sci. Paris, Sér. I*, **320** (1995), 1199–1204.

[13] J. Rubinstein, M. Schatzman, P. Sternberg, Ginzburg-Landau model in thin loops with narrow contrictions, *SIAM J. Appl. Math.*, **64** (2004), 2186–2204.

[14] A. Sili, Asymptotic behavior of the solutions of monotone problems in flat cylinders, *Asymptotic Analysis*, **19** (1999), 19–33.